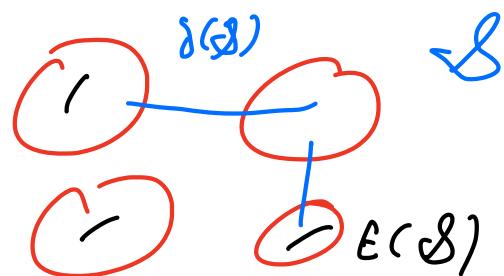


More SDPs :

Today: examples where QP formulation isn't obvious or doesn't exist



Correlation Clustering :

Input: - $G = (V, E)$
 - $w^- : E \rightarrow \mathbb{R}^+$
 - $w^+ : E \rightarrow \mathbb{R}^+$

Feasible solution: Partition \mathcal{S} of V

$\delta(\mathcal{S})$ = edges go between parts of \mathcal{S}

$E(\mathcal{S})$ = edges whose both endpoints in same part of \mathcal{S}

$$\text{Objective: } \max W(\mathcal{S}) = \max \sum_{e \in E(\mathcal{S})} w^+(e) + \sum_{e \in \delta(\mathcal{S})} w^-(e)$$

Simple $1/2$ -approximation: return better of $\mathcal{S}_1 = \{V\}$,
 $\mathcal{S}_2 = \{\{i\} : i \in V\}$

$$\text{value of } \mathcal{S}_1 = W(\mathcal{S}_1) = \sum_{e \in E} w^+(e)$$

$$\text{value of } \mathcal{S}_2 = W(\mathcal{S}_2) = \sum_{e \in E} w^-(e)$$

$$\text{Every partition } \mathcal{S} \text{ has } W(\mathcal{S}) \leq \sum_{e \in E} w^+(e) + \sum_{e \in E} w^-(e)$$

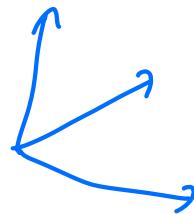
$$\Rightarrow \max(W(\mathcal{S}_1), W(\mathcal{S}_2)) \geq \frac{1}{2} \cdot \text{OPT}$$

Vector Programming Formulation :

$$\max \sum_{\{i,j\} \in E} (w^+(i,j) \langle v_i, v_j \rangle + w^-(i,j) (1 - \langle v_i, v_j \rangle))$$

$$\text{s.t. } v_i \in \{e_1, e_2, \dots, e_n\} \quad \forall i \in \{1, 2, \dots, n\}$$

↑
standard basis vectors



Thm: This is an exact formulation

Prf: Let $\mathcal{S} = (\mathcal{S}_1, \mathcal{S}_2, \dots, \mathcal{S}_k)$ partition of V

For $j \in [k]$ and $i \in \mathcal{S}_j$, set $v_i = e_j$

$$\Rightarrow \sum_{\{i,j\} \in E} (w^+(i,j) \langle v_i, v_j \rangle + w^-(i,j) (1 - \langle v_i, v_j \rangle))$$

$$= \sum_{\{i,j\} \in E(\mathcal{S})} w^+(i,j) + \sum_{\{i,j\} \in E(\mathcal{S})} w^-(i,j) = w(\mathcal{S})$$

Other direction: Let $\{v_i\}$ solution to vector program.

$$\forall j \in [n], \text{ let } \mathcal{S}_j = \{i \in V : v_i = e_j\}$$

$\Rightarrow \{\mathcal{S}_1, \mathcal{S}_2, \dots, \mathcal{S}_n\}$ form partition of value = vector program objective

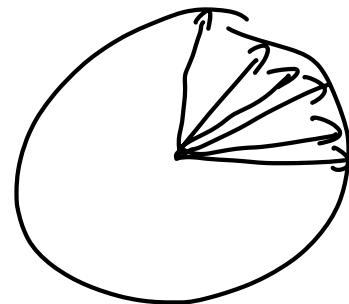
Relax to SDP:

$$\max \sum_{\{(i,j)\} \in E} (\omega^+(i,j) \langle v_i, v_j \rangle + \omega^-(i,j) (1 - \langle v_i, v_j \rangle))$$

$$\text{s.t. } \langle v_i, v_i \rangle = 1 \quad \forall i \in V \quad (\text{unit vectors})$$

$$\langle v_i, v_j \rangle \geq 0 \quad \forall i, j \in V$$

$$v_i \in \mathbb{R}^n \quad \forall i \in V$$



Randings: two random hyperplanes

- Let r_1, r_2 unit vectors drawn independently, uniformly at random from set of all unit vectors

- Let $R_1 = \{i \in V : \langle r_1, v_i \rangle \geq 0, \langle r_2, v_i \rangle \geq 0\}$

$R_2 = \{i \in V : \langle r_1, v_i \rangle \geq 0, \langle r_2, v_i \rangle < 0\}$

$R_3 = \{i \in V : \langle r_1, v_i \rangle < 0, \langle r_2, v_i \rangle \geq 0\}$

$R_4 = \{i \in V : \langle r_1, v_i \rangle < 0, \langle r_2, v_i \rangle < 0\}$

- Return $\mathcal{S} = \{R_1, R_2, R_3, R_4\}$

$$X_{ij} = \begin{cases} 1 & \text{if } i,j \text{ in same cluster} \\ 0 & \text{otherwise} \end{cases}$$

Last time:

$$\Pr[\text{random hyperplane separates } i,j] = \frac{\Theta_{ij}}{\pi}$$

$$\Rightarrow E[X_{ij}] = (1 - \frac{\Theta_{ij}}{\pi})^2$$

$$\Rightarrow E[w(\delta)] = E\left[\sum_{\{i,j\} \in E(\delta)} w^+(i,j) + \sum_{\{i,j\} \in \delta(\delta)} w^-(i,j)\right]$$

$$= E\left[\sum_{\{i,j\} \in E} (w^+(i,j) X_{ij} + w^-(i,j) (1 - X_{ij}))\right]$$

$$= \sum_{\{i,j\} \in E} (w^+(i,j) E[X_{ij}] + w^-(i,j) (1 - E[X_{ij}]))$$

$$= \sum_{\{i,j\} \in E} \left(w^+(\{i,j\}) \left(1 - \frac{\Theta_{ij}}{\pi}\right)^2 + w^-(\{i,j\}) \left(1 - \left(1 - \frac{\Theta_{ij}}{\pi}\right)^2\right) \right)$$

Trig facts: $\left(1 - \frac{\Theta_{ij}}{\pi}\right)^2 \geq \frac{3}{4} \Leftrightarrow \Theta_{ij} \leq \frac{\pi}{2}$

$$1 - \left(1 - \frac{\Theta_{ij}}{\pi}\right)^2 \geq \frac{3}{4} (1 - \cos \Theta_{ij})$$

SPP constraint $\langle v_i, v_j \rangle \geq 0 \Rightarrow \Theta_{ij} \leq \frac{\pi}{2}$

$$\geq \sum_{\{i,j\} \in E} \left(w^+(\{i,j\}) \cdot \frac{3}{4} \cos \Theta_{ij} + w^-(\{i,j\}) \cdot \frac{3}{4} (1 - \cos \Theta_{ij}) \right)$$

$$\begin{aligned}
 &= \frac{3}{4} \sum_{\{(i,j)\} \in E} \left(w^+(i,j) \langle v_i, v_j \rangle + w^-(i,j) (1 - \langle v_i, v_j \rangle) \right) \\
 &= \frac{3}{4} \cdot OPT(SDP)
 \end{aligned}$$

$\Rightarrow \frac{3}{4}$ -approximation

Max-2SAT:

Input: - Variables x_1, x_2, \dots, x_n
 - CNF clauses C_1, C_2, \dots, C_m , each with 2 literals
 $(x_i \vee \bar{x}_j), (\bar{x}_i \vee x_j), (x_i \vee x_j), \dots$

Feasible solution: Assignment $\{x_1, \dots, x_n\} \rightarrow \{T, F\}$

Objective: $\max \# \text{satisfied (true) clauses}$

Note: 2SAT not NP-hard, but Max-2SAT is!

Want to write **strict** quadratic program, where

$y_i = -1$ corresponds to $x_i = T$

$y_i = 1$ corresponds to $x_i = F$

Problem: Symmetry!

$C = X_i \vee \overline{X_j} \Rightarrow y_i = -1, y_j = 1$ should be ok, but
 $y_i = 1, y_j = -1$ should not.

But strictness means can only look at products!

Solution: add "dummy variable" $y_T \in \{-1, 1\}$

$y_i = y_T$ corresponds to $X_i = T$

$y_i = -y_T$ corresponds to $X_i = F$

Consider clause $X_i \vee \overline{X_j}$, values y_i, y_j, y_T :

$$\frac{3 + y_i y_T + y_j y_T - y_i y_j}{4} = \begin{cases} 0 & \text{if } y_i = y_j = -y_T \\ 1 & \text{otherwise} \end{cases}$$

Clause $X_i \vee \overline{X_j}$, values y_i, y_j, y_T : same thing, negate y_j :

$$\frac{3 + y_i y_T - y_j y_T + y_i y_j}{4} = \begin{cases} 0 & \text{if } y_i = -y_T, y_j = y_T \\ 1 & \text{otherwise} \end{cases}$$

Clause $\bar{x}_i \vee x_j$, values y_i, y_j, y_T :

$$\frac{3 - y_i y_T + y_j y_T + y_i y_j}{4} = \begin{cases} 0 & \text{if } y_i = y_T, y_j = -y_T \\ 1 & \text{otherwise} \end{cases}$$

Clause $\bar{x}_i \vee \bar{x}_j$, values y_i, y_j, y_T :

$$\frac{3 - y_i y_T - y_j y_T - y_i y_j}{4} = \begin{cases} 0 & \text{if } y_i = y_j = -y_T \\ 1 & \text{otherwise} \end{cases}$$

Strict Quadratic Programming Formulation:

$$\max \sum_{\substack{\text{clauses } x_i \vee x_j}} \frac{3 + y_i y_T + y_j y_T - y_i y_j}{4} + \sum_{\substack{\text{clauses } x_i \vee \bar{x}_j}} \frac{3 + y_i y_T - y_j y_T + y_i y_j}{4} \\ + \sum_{\substack{\text{clauses} \\ \bar{x}_i \vee x_j}} \frac{3 - y_i y_T + y_j y_T + y_i y_j}{4} + \sum_{\substack{\text{clauses} \\ \bar{x}_i \vee \bar{x}_j}} \frac{3 - y_i y_T - y_j y_T - y_i y_j}{4}$$

$$\text{s.t. } y_i^2 = 1 \quad \forall i \in [n]$$

$$y_T^2 = 1$$

Relax to SDP:

$$\begin{aligned}
 & \max \sum_{\substack{\text{(clauses)} \\ x_i \vee x_j}} \frac{3 + \langle v_i, v_T \rangle + \langle v_j, v_T \rangle - \langle v_i, v_j \rangle}{4} + \sum_{\substack{\text{(clauses)} \\ x_i \vee \bar{x}_j}} \frac{3 + \langle v_i, v_T \rangle - \langle v_j, v_T \rangle + \langle v_i, v_j \rangle}{4} \\
 & + \sum_{\substack{\text{(clauses)} \\ \bar{x}_i \vee x_j}} \frac{3 - \langle v_i, v_T \rangle + \langle v_j, v_T \rangle + \langle v_i, v_j \rangle}{4} + \sum_{\substack{\text{(clauses)} \\ \bar{x}_i \vee \bar{x}_j}} \frac{3 - \langle v_i, v_T \rangle - \langle v_j, v_T \rangle - \langle v_i, v_j \rangle}{4}
 \end{aligned}$$

$$\text{s.t. } \langle v_i, v_i \rangle = 1 \quad \forall i \in [n]$$

$$v_i \in \mathbb{R}^n \quad \forall i \in [n]$$

$$\langle v_T, v_T \rangle = 1$$

$$v_T \in \mathbb{R}^n$$

$$\text{Relaxation} \Rightarrow \text{OPT}(SDP) \geq \text{OPT}$$

Rounding: random hyperplane!

- choose unit vector $r \in \mathbb{R}^n$ u.a.r.

$$- \text{set } x_i = \begin{cases} T & \text{if } \text{sign}(\langle r, v_i \rangle) = \text{sign}(\langle r, v_T \rangle) \\ F & \text{if } \text{sign}(\langle r, v_i \rangle) \neq \text{sign}(\langle r, v_T \rangle) \end{cases}$$

(consider clause $x_i \vee x_j$ (other types similar))

$$\frac{3 + \langle v_i, v_T \rangle + \langle v_j, v_T \rangle - \langle v_i, v_j \rangle}{4} = \frac{1}{4} ((1 + \langle v_i, v_T \rangle) + (1 + \langle v_j, v_T \rangle) + (1 - \langle v_i, v_j \rangle))$$

\Rightarrow all terms $(1 \pm \langle v_k, v_\ell \rangle)$ for some k, l (possibly ≤ 7)

Analyze each term

$$\text{Recall } \alpha_{\text{GW}} = \inf_{0 \leq \theta \leq \pi} \frac{2\theta}{\pi(1 - \cos \theta)}$$

Consider $1 - \langle v_k, v_l \rangle$

\Rightarrow contribution to SDP is $1 - \langle v_k, v_l \rangle = 1 - \cos \theta_{kl}$

$$\Pr[v_k, v_l \text{ separated by hyperplane}] = \frac{\theta_{kl}}{\pi}$$

$$\Rightarrow E[1 - \gamma_k \gamma_l] = 2 \cdot \Pr[v_k, v_l \text{ separated}] = 2 \frac{\theta_{kl}}{\pi} \geq \alpha_{\text{GW}} (1 - \cos \theta_{kl})$$

\Rightarrow in expectation, rounded solution gets $\geq \alpha_{\text{GW}} \cdot \text{SDP}$

Consider $1 + \langle v_k, v_l \rangle$

\Rightarrow contribution to SDP = $1 + \cos \theta_{kl}$

$$\text{Contribution to rounded solution: } E[1 + \gamma_k \gamma_l] = 2 \left(1 - \frac{\theta_{kl}}{\pi}\right)$$

$$\Rightarrow \text{ratio b/w contributions} = \frac{2 \left(1 - \frac{\theta_{kl}}{\pi}\right)}{1 + \cos \theta_{kl}} = \frac{2(\pi - \theta_{kl})}{\pi(1 + \cos \theta_{kl})}$$

$$\text{Let } \theta' = \pi - \theta_{kl} \Rightarrow \frac{2 \theta'}{\pi(1 - \cos \theta')} \geq \alpha_{\text{GW}}$$

$$\cos(\pi - \theta) = -\cos \theta$$

\Rightarrow rounded sol. $\geq \alpha_{\text{GW}} \cdot \text{SDP}$