

Lecture 14: Basic Graph Algorithms II

Michael Dinitz

October 10, 2024

601.433/633 Introduction to Algorithms

Introduction

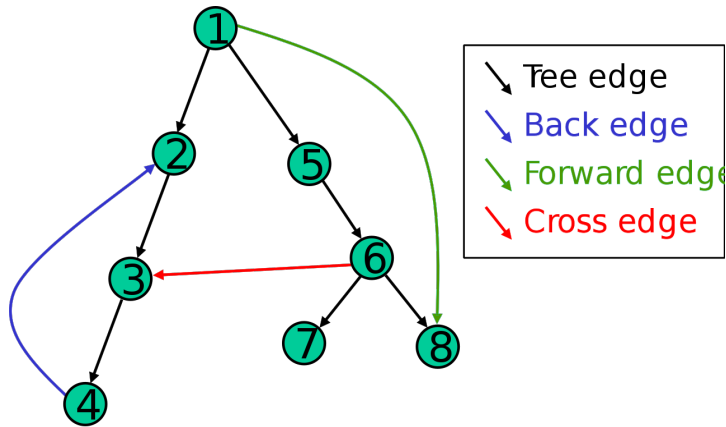
Last time: BFS and DFS

Today: Topological Sort, Strongly Connected Components

- ▶ Both very classical and important uses of DFS!

Edge Types

DFS naturally gives a spanning forest: edge (v, u) if $\text{DFS}(v)$ calls $\text{DFS}(u)$



Forward Edges: (v, u) such that u descendent of v (includes tree edges)

$$start(v) < start(u) < finish(u) < finish(v)$$

Back Edges: (v, u) such that u an ancestor of v

$$start(u) < start(v) < finish(v) < finish(u)$$

Cross Edges: (v, u) such that u neither a descendent nor an ancestor of v

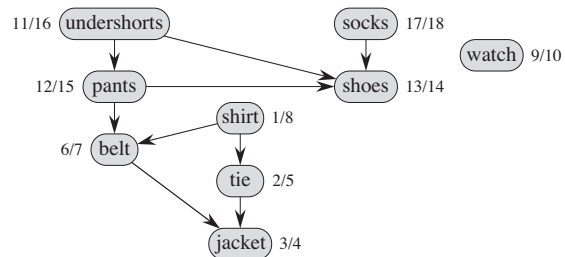
$$start(u) < finish(u) < start(v) < finish(v)$$

Topological Sort

Definitions

Definition

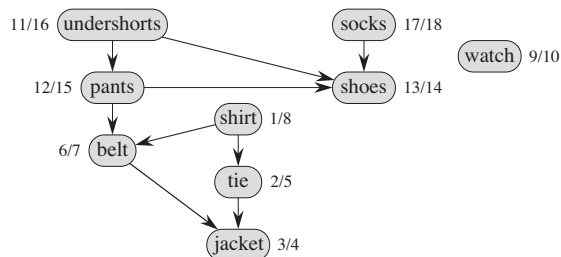
A directed graph G is a *Directed Acyclic Graph (DAG)* if it has no directed cycles.



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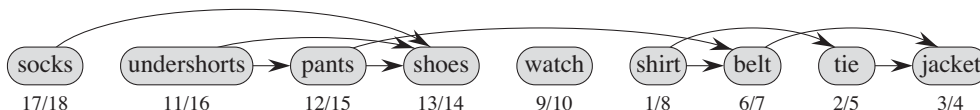
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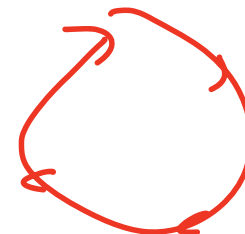
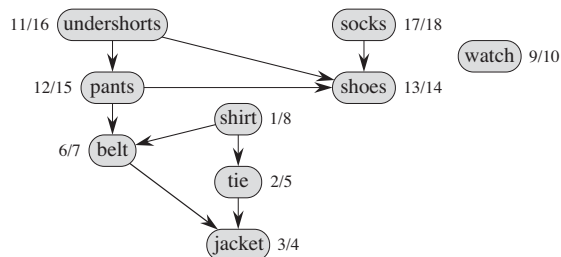
A *topological sort* v_1, v_2, \dots, v_n of a DAG is an ordering of the vertices such that all edges are of the form (v_i, v_j) with $i < j$.



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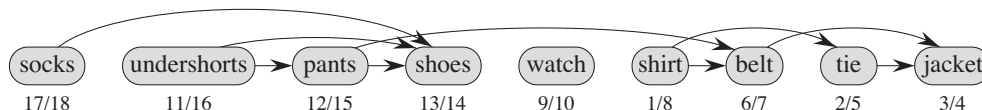
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Q: Can we always topological sort a DAG? How fast?

Topological Sort

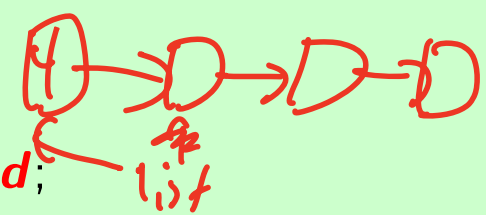
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Topological Sort

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```
DFS( $\mathbf{G}$ ) {  
  list  $\rightarrow$  head = NULL;  
   $t = 0$ ;  
  for all  $\mathbf{v} \in \mathbf{V}$  {  
    start( $\mathbf{v}$ ) =  $0$ ;  
    finish( $\mathbf{v}$ ) =  $0$ ;  
  }  
  while  $\exists \mathbf{v} \in \mathbf{V}$  with start( $\mathbf{v}$ ) =  $0$  {  
    DFS( $\mathbf{v}$ );  
  }  
}
```

```
DFS( $\mathbf{v}$ ) {  
   $t = t + 1$ ;  
  start( $\mathbf{v}$ ) =  $t$ ;  
  for each edge  $(\mathbf{v}, \mathbf{u}) \in \mathbf{A}[\mathbf{v}]$  {  
    if start( $\mathbf{u}$ ) ==  $0$  then DFS( $\mathbf{u}$ );  
  }  
   $t = t + 1$ ;  
  finish( $\mathbf{v}$ ) =  $t$ ;  
  temp = list  $\rightarrow$  head;  
  list  $\rightarrow$  head =  $\mathbf{v}$ ;  
  list  $\rightarrow$  head  $\rightarrow$  next = temp;  
}
```



Characterizing DAGs

Theorem

A directed graph \mathbf{G} is a DAG if and only if $DFS(\mathbf{G})$ has no back edges.

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Proof.

Only if (\Rightarrow): contrapositive. If G has a back edge:

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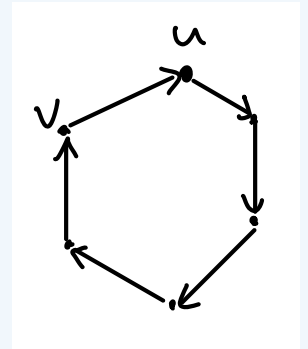
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If (\Leftarrow): contrapositive. If \mathbf{G} has a directed cycle \mathbf{C} :

- ▶ Let $u \in \mathbf{C}$ with minimum start value, v predecessor in cycle
- ▶ All nodes in \mathbf{C} reachable from $u \implies$ all nodes in \mathbf{C} descendants of u
- ▶ (v, u) a back edge



Topological Sort Analysis

Correctness:

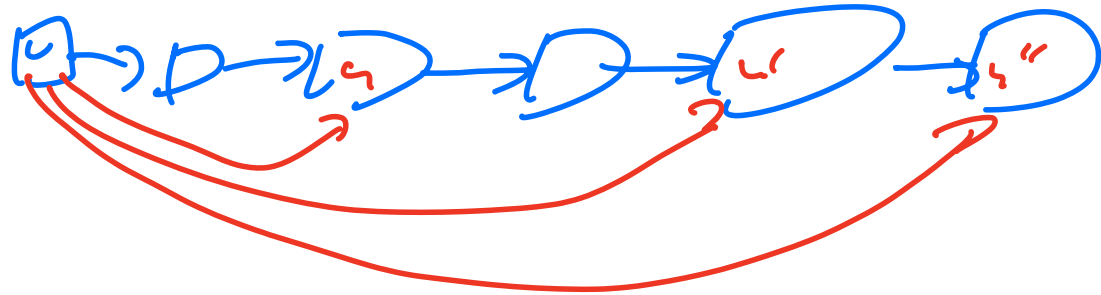
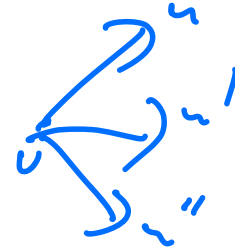
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Running Time:

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Running Time: Same as DFS! $O(m + n)$

Strongly Connected Components (SCC)

Definitions

Another application of DFS. “Kosaraju’s Algorithm”: Developed by Rao Kosaraju, professor emeritus at JHU CS!

$G = (V, E)$ a directed graph.

Definition

$C \subseteq V$ is a *strongly connected component (SCC)* if it is a *maximal* subset such that for all $u, v \in C$, u can reach v and vice versa (bireachable).

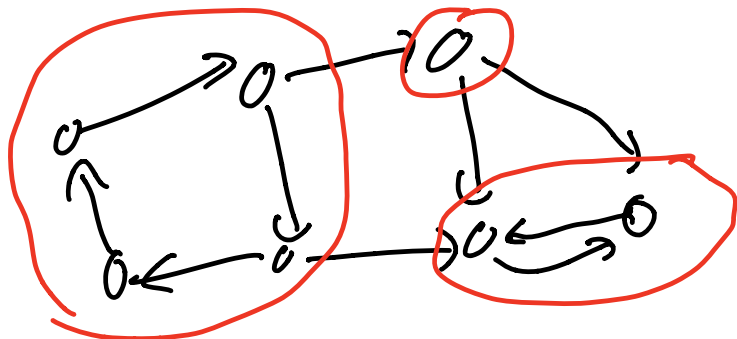
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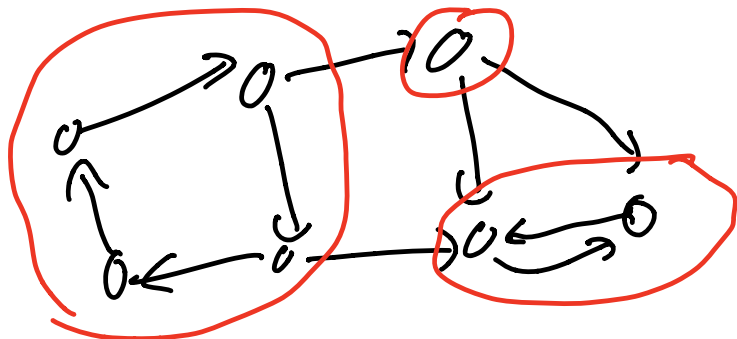
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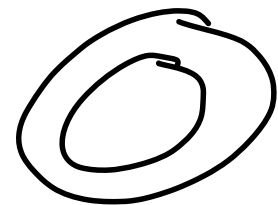
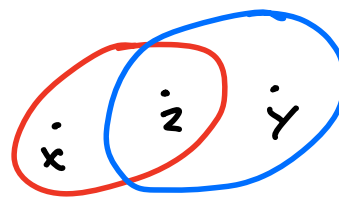
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Fact: There is a *unique* partition of V into SCCs



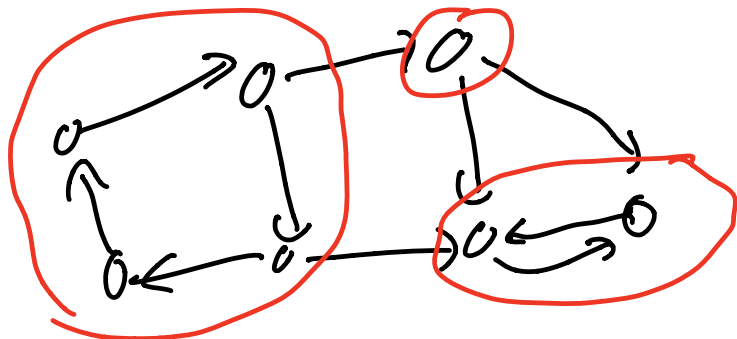
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Fact: There is a *unique* partition of V into SCCs

Proof: Bireachability is an equivalence relation: if u and v are bireachable, and v and w are bireachable, then u and w are bireachable.

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Problem: Given \mathbf{G} , compute SCCs (partition \mathbf{V} into the SCCs)

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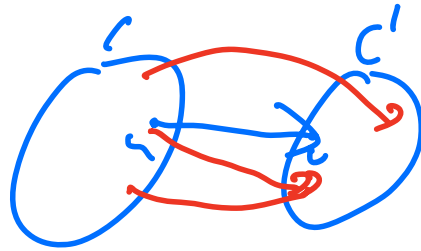
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Can we do better? $O(m + n)$?

Graph of SCCs

Definition: Let \hat{G} be graph of SCCs:

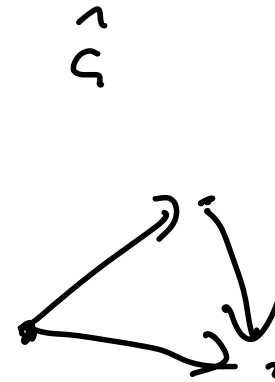
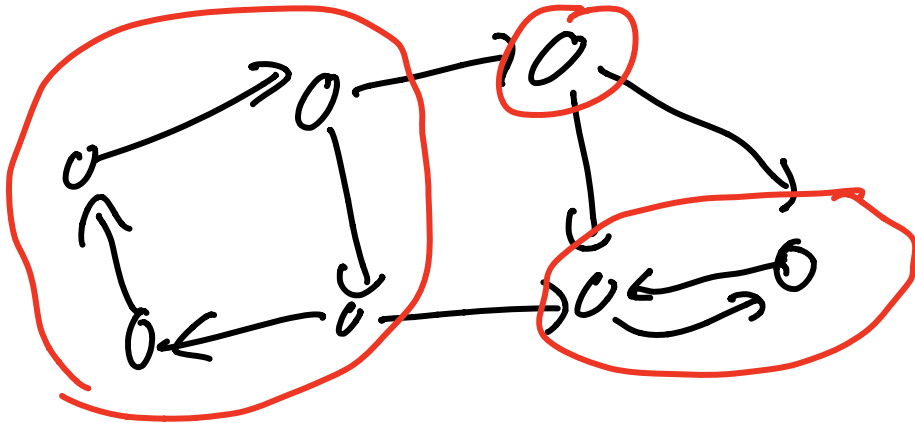
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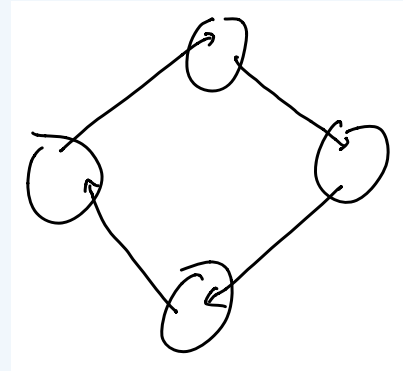
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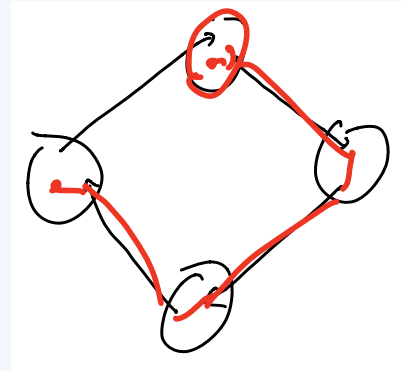
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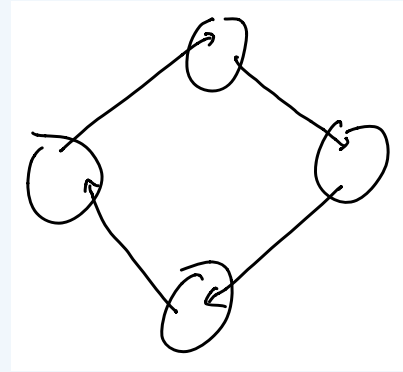
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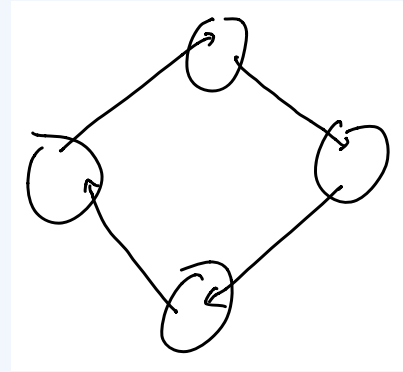
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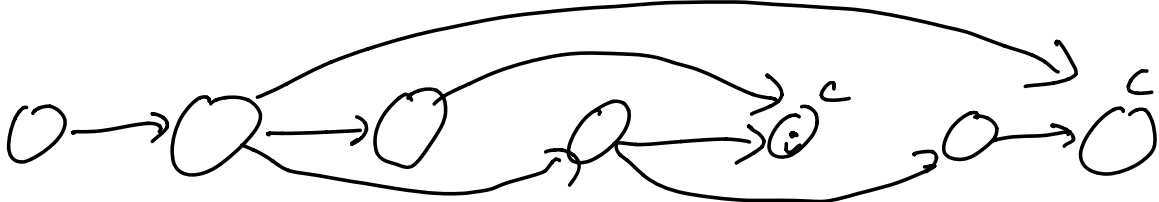
$\implies v(\mathbf{C})$ not an SCC for $v(\mathbf{C}) \in H$

Contradiction!



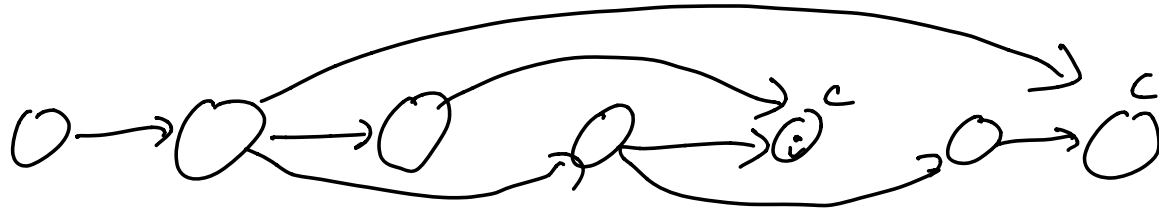
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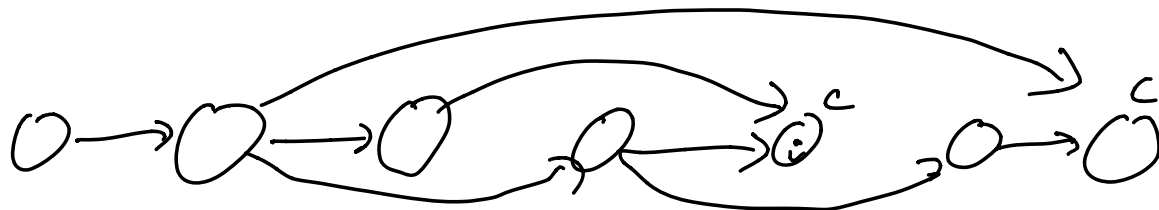


Definition: SCC C is a *sink* SCC if no outgoing edges *in \hat{G}*

- ▶ Claim: At least one sink SCC exists

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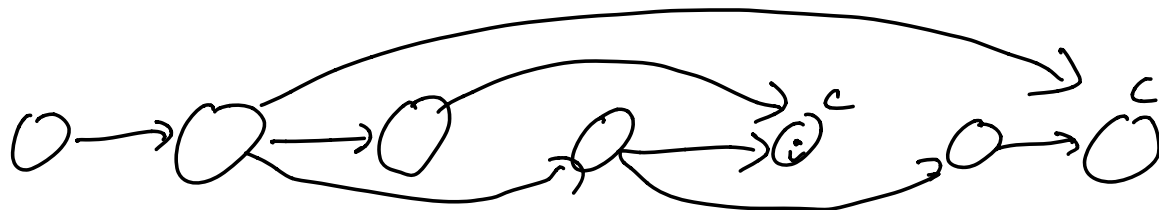


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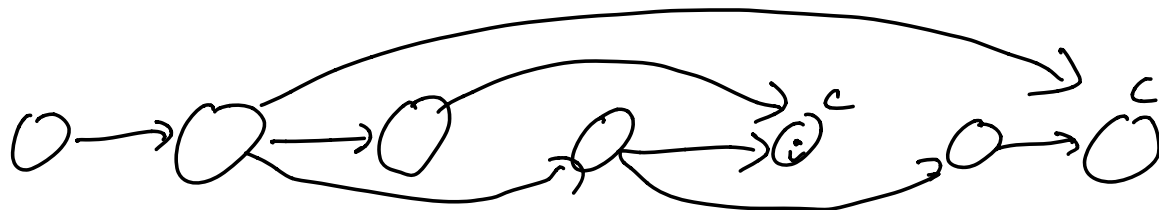
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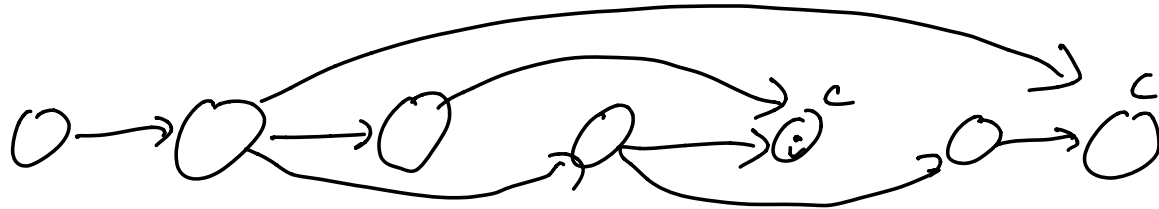
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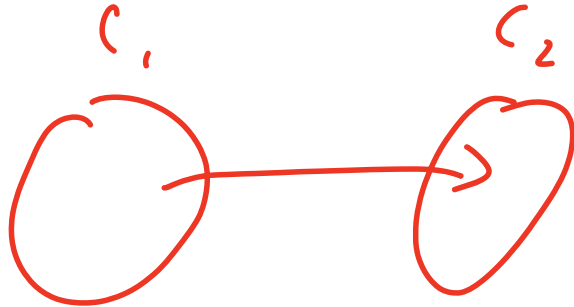
Strategy: find node in sink SCC, run DFS, remove nodes found, repeat

SCCs and DFS

Run DFS(\mathbf{G}), and let $\mathbf{finish}(C) = \max_{v \in C} \mathbf{finish}(v)$

Lemma

Let C_1, C_2 distinct SCCs s.t. $(v(C_1), v(C_2)) \in E(\hat{\mathbf{G}})$. Then $\mathbf{finish}(C_1) > \mathbf{finish}(C_2)$.



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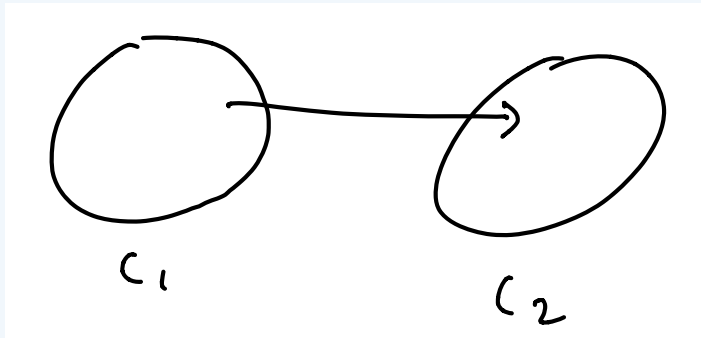
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Let $x \in C_1 \cup C_2$ be first node encountered by DFS



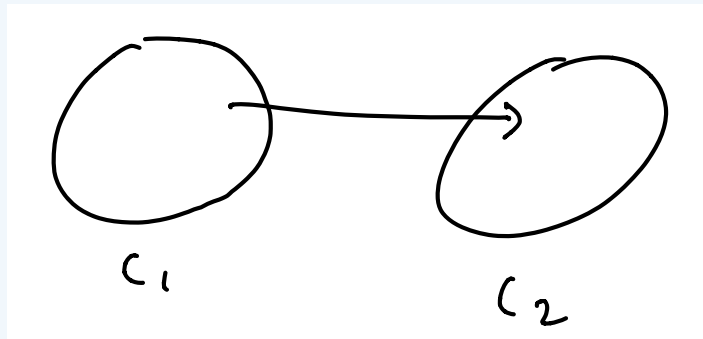
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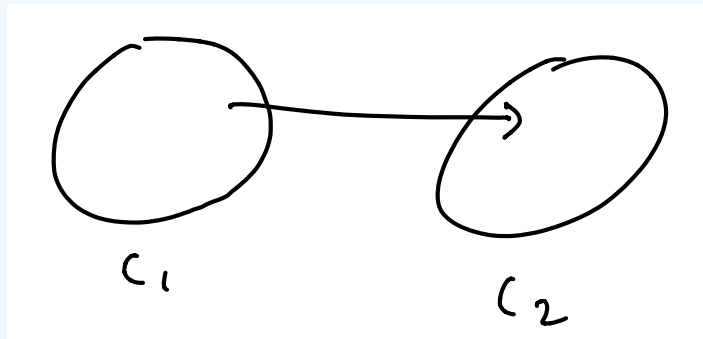
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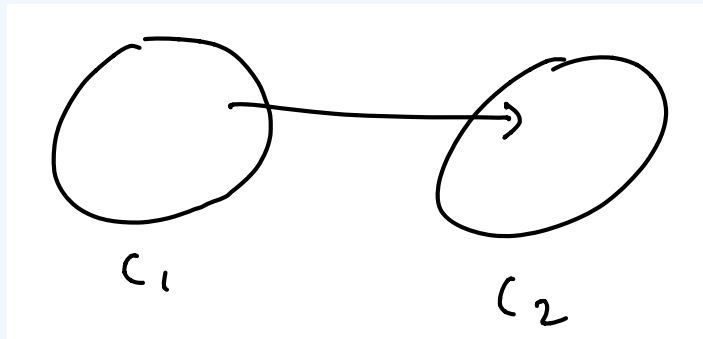
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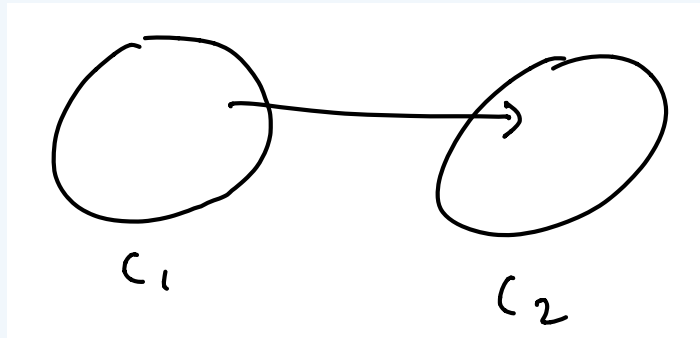
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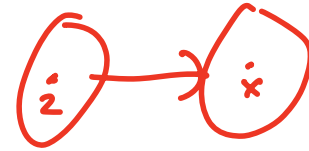
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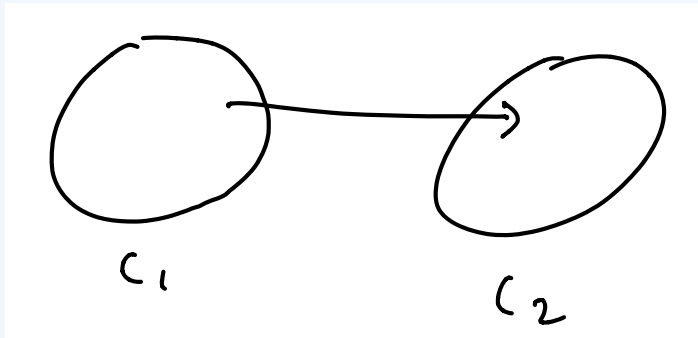
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So node of *max* finishing time in a *source* SCC (no incoming edges in \hat{G}).

Useful Corollary

Run $\text{DFS}(\mathbf{G})$, and let $\mathbf{finish}(\mathbf{C}) = \max_{v \in \mathbf{C}} \mathbf{finish}(v)$.

Corollary

Let \mathcal{C} be collection of all SCCs of \mathbf{G} , and let $\mathcal{C}' \subseteq \mathcal{C}$. Let $\mathbf{G}' = \mathbf{G} \setminus (\bigcup_{\mathbf{C} \in \mathcal{C}'} \mathbf{C})$. Then the node $\mathbf{v} = \mathbf{argmax}_{u \in \bigcup_{\mathbf{C} \in \mathcal{C} \setminus \mathcal{C}'} \mathbf{C}} \mathbf{finish}(u)$ is in an SCC of \mathbf{G} that is a source SCC of \mathbf{G}' .

Useful Corollary

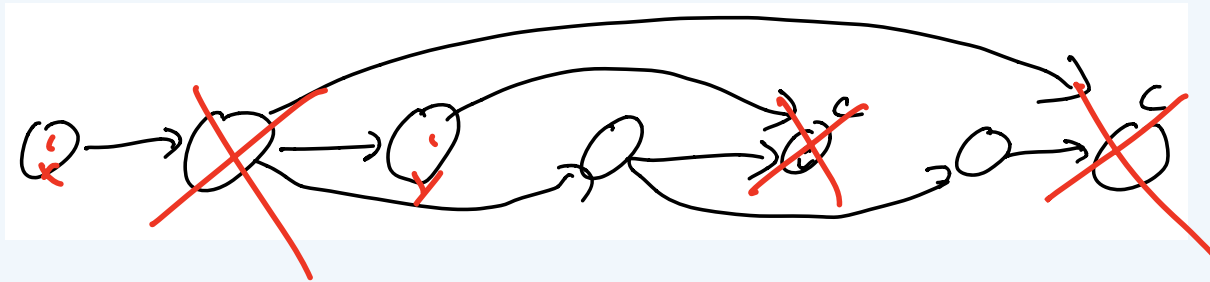
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Let \mathbf{C} be collection of all SCCs of \mathbf{G} , and let $\mathbf{C}' \subseteq \mathbf{C}$. Let $\mathbf{G}' = \mathbf{G} \setminus (\bigcup_{\mathbf{C} \in \mathbf{C}'} \mathbf{C})$. Then the node $v = \mathbf{argmax}_{u \in \bigcup_{\mathbf{C} \in \mathbf{C} \setminus \mathbf{C}'} \mathbf{C}} \mathbf{finish}(u)$ is in an SCC of \mathbf{G} that is a source SCC of \mathbf{G}' .

Proof.

Clearly SCCs of \mathbf{G}' are precisely $\mathbf{C} \setminus \mathbf{C}'$:



Useful Corollary

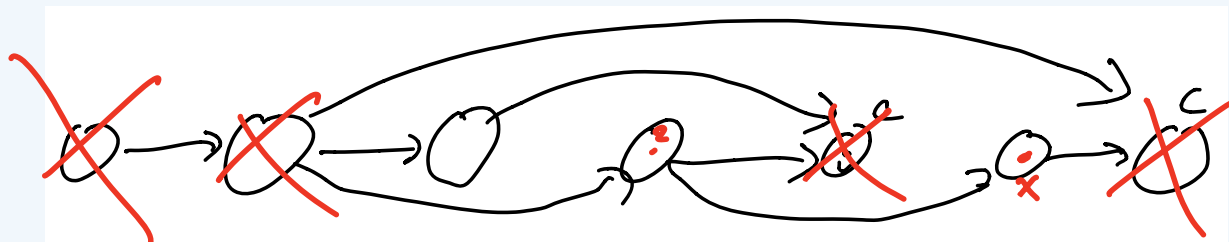
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Lemma \implies node remaining with max finish time in a ~~sink~~^{source} SCC of what remains. □

Kosaraju's Algorithm

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- ▶ DFS(G^T) to get finishing times and order π on V from ~~smallest~~ finishing time to ~~largest~~ *largest to smallest*
- ▶ Set $mark(v) = \mathbf{False}$ for all $v \in V$
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Running Time: $O(m + n)$

Correctness Sketch

Let C_1, C_2, \dots, C_k be sets identified by algorithm (in order)

Theorem

C_i is a sink SCC of $G \setminus \left(\bigcup_{j=1}^{i-1} C_j \right)$, and an SCC of G .

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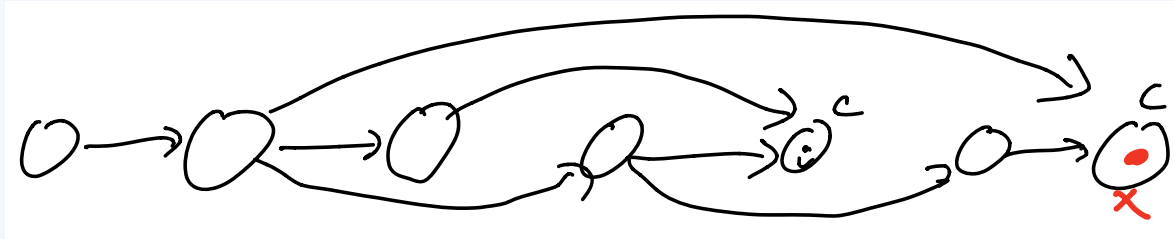
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Base case: $i = 1$. By previous argument, largest finishing time in $G^T \implies$ in sink SCC of $G \implies C_1$ is sink SCC of G

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Let $\mathbf{C}_1, \mathbf{C}_2, \dots, \mathbf{C}_k$ be sets identified by algorithm (in order)

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\mathbf{C}_i is a sink SCC of $\mathbf{G} \setminus \left(\bigcup_{j=1}^{i-1} \mathbf{C}_j\right)$, and an SCC of \mathbf{G} .

Proof Sketch.

Induction on i .

Base case: $i = 1$. By previous argument, largest finishing time in $\mathbf{G}^T \implies$ in sink SCC of $\mathbf{G} \implies \mathbf{C}_1$ is sink SCC of \mathbf{G}

Inductive case: Let $i > 1$. Let \mathbf{v} unmarked node with largest finishing time.

- ▶ By induction, subgraph of unmarked nodes is \mathbf{G} minus $i - 1$ SCCs of \mathbf{G}
- ▶ Corollary $\implies \mathbf{v}$ must be in sink SCC of unmarked nodes so get an SCC of unmarked nodes when run DFS
- ▶ Corollary \implies SCC of original graph